

## Emerging Technologies for Post-earthquake Reconnaissance

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- Many collaborators from the U.S., Japan, Turkey, Taiwan, etc. too numerous to be listed here.



# Post-earthquake reconnaissance and earthquake engineering



Post earthquake reconnaissance will continue to impact the field of earthquake engineering, provided it documents scientifically the effects of earthquakes.





- 1. Background: GEES
- 2. GPS/GIS/Video/Photo Tools
- 3. NEES Data and Metadata
- 4. Collaboratory?



#### Geotechnical Earthquake Engineering Server http://geoinfo.usc.edu/gees





## **GEES post-earthquake reconnaissances**

| Earthquake name       | Earthquake<br>date | Arrival date of<br>Reconnaissance<br>team | Report<br>release<br>date | Days |
|-----------------------|--------------------|---|---------------------------|------|
| Hyogoken-Nanbu, Japan | 01/17/95           | 01/27/95                                  | 02/05/95                  | 9    |
| Kocaeli, Turkey       | 08/17/99           | 08/24/99                                  | 09/03/99                  | 10   |
| Chichi, Taiwan        | 09/21/99           | 09/29/99                                  | 10/08/99                  | 9    |
| Ducze, Turkey         | 11/12/99           | 11/17/99                                  | 11/25/99                  | 8    |
| Bhuj, India           | 01/26/01           | 02/12/01                                  | 03/01/01                  | 17   |

- January 1995 report was one of the first earthquake reconnaissance reports on the Internet (Mosaic was released in 1993).
- Reports have evolved since 1995.



#### **GEES** - India





#### **GIS-GPS-Photo**



Figure 1. In Ahmedabad, the aircraft used for flight over, and the aerial survey reconnaissance team. From left to right, Colonel H. Singh, J. P. Bardet, Capt. Rajiv Nanavaty, and J. P. Singh (2/12/01 6.18:65 PM, N23.06806 E/22.15190).





Figure 14. Closeup of tracklog and location of figures in the vicinity of Navalkhi port.



Figure 15. General view of Navalkhi port located in the Gulf of Kachchh, 25 km to the Southeast of Ghandidham (2/12/01 10:48:25 AM, N22.92851 E70.43793).



Figure 30. Closeup of tracklog and location of figures in the vicinity of Anjar.



Figure 31. Very few masonry buildings were left standing 2 km to the Southeast of the Anjar (2/12/01 11:14:50 AM, N23.10079 E70.05062).

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#### Video

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## **Web-Report Generation using Excel**





#### **GIS-IMS-Information integration**



M<sub>w</sub> 7.7 Bhuj, India, Earthquake of January 26, 2001



#### **Geo-referencing Videos in the field**





#### **Geo-referenced Video on the Web**





## **Need for Metadata Web Reporting**





## Why new tools for post-earthquake reconnaissance?

- Capture perishable, relevant, quantitative and qualitative information after earthquakes
- Improve/accelerate dataflow from the field to the digital library and public
  - Integrate various data and tools:
    - Videos
    - Pictures
    - GPS (coordinates and time)
    - Voice
    - Electronic notebooks/PDA data
- Create a reverse dataflow from a command center to the field
  - Satellite imagery/remote sensing data
  - Other information
- Curate information for posterity



# NEES George E. Brown, Jr., Network for Earthquake Engineering Simulation





## The NEES Data Experience

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|   | CGM Dat                    |   | Privansh                            | 1 Singh (psingh@subsurfaceconsultants.com)  |  |  | <u>Raw Data Files i</u>        | <u>n Prototype Units</u>                       |   |
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## Metadata and Data

- Metadata = data about data
- Metadata has different meanings depending on expertise domains
- In Earthquake Engineering, metadata document the process of data generation so that one can understand how data were obtained
- Metadata models glue together various data
- Fuzzy distinction between data and metadata?



## Data Language: XML and XML Schemas

- The eXtensible Markup Language (XML) (http://www.w3.org/XML/) has become a standard for exchanging data.
- XML is a meta-markup language that consists of a set of rules for creating semantic tags used to describe data
  - <element attribute= ...> ....</element>.
- XML
  - wide acceptance from the computer industry, Microsoft, AutoCAD, IBM and Oracle.
  - widely used for defining data models.
  - object-oriented structure and readability extensibility.
  - \_
- XML Schemas (http://www.w3.org/XML/Schema)
  - provide a means for defining the structure, content and semantics of data models.
  - components such as type definitions and element declarations.
  - used to assess the validity of well-formed attributes, and may specify default values for attributes and attribute types.
- The schema-validity assessment checks the constraints on attributes, and can be used to model the constraints imposed on data models.



## Metadata Languages: RDF

- RDF = Resource Description Framework (http://www.w3.org/RDF/)
- developed by the World-Wide Web Consortium (W3C),
- Metadata interoperability across different communities.
- RDF provides a Syntax and Schema specification.
- RDF key concepts
  - graph data model
  - URI (Uniform Resource Identifier)-based vocabulary and node identification
  - data types
  - Literals
  - XML serialization syntax
  - expression of simple facts and entailment.
- RDF extends the XML model and syntax for describing resources.
- RDF utilizes the XML namespaces and allows to identify uniquely a set of properties.



## Metadata Languages: OWL

- Ontologies define a common vocabulary for researchers who need to share information in a technical domain.
- Machine-interpretable definitions of basic concepts in a domain and relations among them.
- Originated in Artificial-Intelligence, ontologies have become common on the World-Wide Web to categorize information on large Web sites (e.g., Yahoo!) and products for sale (e.g., Amazon.com).
- Many disciplines now develop ontologies which domain experts can use to share and annotate information
  - SNOMED in Medicine
- OWL (Web Ontology Language) is for processing the content of information instead of just presenting information to humans.
- OWL facilitates greater machine interpretability of Web content than XML and RDF by providing additional vocabulary and a formal semantics.



## How to define and relate NEES objects





## Metadata modeling using Protégé

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# NEES Metadata Attributes and Relationships

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|------------------|--|---------------------|-----------------------------------|-----------------------|---|
| Attribute        | Bhei deimition   | Data type<br>String | Broingt                           | s(es)                 |   |
| address          | mailing address for Person and Organization                    | String              | Person Organ                      | ization               |   |
| contractID       | a contract number different NEESCode                           | String              | Project                           |                       |   |
| description      | a descriptive text, consisting of a few sentences and          | String              | File, Specimen, Equipment, S      | ensor. Configuration  |   |
|                  | corresponding to name.   |                     | Organization, Software, Activity, | Organization, Publica |   |
| email            | email address  |                     | Person                            |                       |   |
| endDate          | date of planned completion for Task and Project                | Date                | Project, Ta                       | isk                   |   |
| endDateTime      | date and time of actual completion for Event                   | DateTime            | Event                             |                       |   |
| fileType         | type of file   | String Enumeration  | File                              |                       |   |
| firstName        | first name of a Person   | String              | Person                            |                       |   |
| homePage         | web page   | URI                 | Person, Organizatio               | n, Software           |   |
| keyWords         | key workds characterizing a Project and/or Publication         | String              | Publication, F                    | roject                |   |
| lastName         | last name of a Person  | String              | Person                            | -                     |   |
| name             | a short description like a figure caption or a section heading | Float               | EQMOTIO                           | n<br>Activity Specime |   |
| nume             | usually complemented by <i>description</i>                     |                     | File, Organization, Configuration | A the last a          | Deint te instance of                              |
| NEESCode         | a code reserved for the NEES consortium                        | U                   | lass calling                      | Attribute             | Point to instances of                             |
| objectives       | a list of Projects objectives                                  | Publication, S      | oftware                           | is authored by        | Person, Organization                              |
| otherInformation | additional information for a Sensor                            | Sensor              |                                   | is calibrated in      | File  |
| partNumber       | model number for equipment                                     | 5011501             |                                   | is_culloruleu_in      | 1 lic   |
| phone            | phone number including type of phone                           | Organization        |                                   | is composed of        | Organization                                      |
| publicationYear  | year of publication for a Publication                          | Task Event (        | Configuration                     | is configured by      | Configuration                                     |
| releaseDate      | release date for a Software                                    |                     |                                   | is_conjigureu_by      |   |
| role             | role of a person in a Site and/or Activity                     | Configuration       | , Specimen, Software,             | is_described_in       | File, Publication                                 |
| samplingkale     | sampling rate in time series of earthquake motion              | Equipment, Pr       | oiect. Task. Event                |                       |   |
| sensorRange      | range of a sensor including units                              |                     |                                   | ::                    | D   |
| sensorType       | type of sensor   | w orker             |                                   | is_laentifiea_as      | Person  |
| serialNumber     | serial number unique to a piece of equipment                   | Project             |                                   | is granted to         | Organization                                      |
| startDate        | date at the scheduled start of a Project and/ Task             | Snaaiman            |                                   | is instrumented with  | Sensor Label                                      |
| startDateTime    | date and time at the actual start of an Event                  | speemen             |                                   | is_instrumentea_with  | Selisol, Label                                    |
| title            | tilte of a Person  | Label               |                                   | is_label_of           | Specimen, Equipment, Sensor, Software             |
| uom              | unit of measure for the time series in EQMotion                | Equipment           |                                   | is made up of         | Equipment   |
| URI              | Universal Record Identifier                                    | Equipment           |                                   | is_muue_up_0j         | Equipment   |
|                  |  | Equipment           |                                   | is_manufactured_by    | Organization, Person                              |
|                  |  | Equipment           |                                   | is_owned_by           | Person, Organization                              |
|                  |  | Project, Task,      | Event                             | is_performed_at       | Organization                                      |
|                  |  | Project, Task,      | Event                             | is performed by       | Worker  |
|                  |  | Configuration       |                                   | is prepared for       | Label, Specimen, Equipment, Sensor, Software      |
|                  |  | Project             |                                   | is sponsored by       | Organization                                      |
|                  |  | Project Task        |                                   | is_sponsored_oy       | Task Event  |
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|                  |  | Organization        | <b>D</b> (                        | is_workplace_of       |   |
|                  |  | Project, Task,      | Event                             | originates_from       | Project, Task, Event                              |
|                  |  | Event               |                                   | produces              | File, Software, Specimen, Equipment, Publication, |
|                  |  |                     |                                   |                       | Configuration                                     |



## **NEES Metadata Relationships**





## **NEES miniMOST Experiment**





## **NEES objects for miniMOST**





## **NEES miniMOST**

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| Drawing of test beam                 |  |  |
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| 🗘 Folder of files generated by DAQ   |  |  |
| 🗘 List of parts to be manufactured ٤ |  |  |
| 🗘 Log file generated by DAQ comp     |  |  |
| 🗘 Matlab code NCSA_Comp_Site         | Name   | Description  |
| 🍄 Matlab code UIUC_Exp_Site. m 1     | Photograph of the overall setup of miniMOST                    | The photograph shows the test beam, the actuator, and the LVDT |
| 🐺 Metadata file generated by the DA  |  | sensor covered by a plexiglass enclosure                       |
| NEESpop_requirement                  | FileTyne   |  |
| Parts of miniMOST experiments        |  |  |
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| Photograph of actuator               |  |  |
| Photograph of beam anchorage         | StartDateTime  |  |
| Photograph of caple SH6868EP         |  |  |
| Photograph of load call              |  |  |
| Photograph of LVDT and signal c      |  |  |
| Photograph of NLBNC connection       |  |  |
| Photograph of NI PCL7342             | http://gees.usc.edu/NEES/MetadataModel/miniMOST/miniMOST/UIUC  | C/figures/Mini_MOST.jpg  |
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| Photograph of overall setup for m.   |  |  |
| Photograph of SHC68 cable            |  |  |
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| 🗘 Photograph of the Omega meter      |  |  |
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| 🗘 Plane view of test setup           |  |  |
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| 🍄 Top view of actuator and beam 📃 💌  |  |  |
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## **NEES miniMOST Web report**

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| George E. Brown, Jr. Network for Earthquake Engineering Simulation (NEES)   |  | George E. Brown, Jr. Netw  | rork for Earthquake Engineering Simulation (NEES)  | George E. Brown, Jr. Network for Earthquake Engineering Simulation (NEES)   |   |  |
| Home  | Project Title:   | Hama   | Detail of project can be accessed through  | Home  | Setup of physical model   |  |
| I Done<br>I Project: miniMOST-new<br>I Task 1<br>Event 1<br>Event 2<br>Event 3<br>Event 4<br>I Task 2<br>Event 4<br>I Task 2<br>Event 2<br>I Task 2 | Project Thie:<br>miniMOST-new<br>Description: The main purpose of the mini-MOST<br>experiment is to show the capability of major NEESgrid<br>service components using a small-scale physical<br>experiment setup. The Multi-site Online Simulation Test<br>(MOST) was conducted in July 30, 2003. MOST<br>consisted of performing collaboratively tests and<br>simulations at three different locations, each test/simulation<br>modeling different parts of a frame. Compared to MOST,<br>minIMOST uses small (min) portable equipment, which<br>can be easily moved to various places. However, the<br>software involved in this experiment is similar to what was<br>used for the MOST experiment and provides the same<br>level of functionality and services. Therefore, minIMOST i<br>a platform for students and researchers to become familiar<br>with the NEESgrid software and to gain first-hand<br>experience before conducting full-scale experiment. | I onne I project: miniMOST-new I Task 1 Event 1 Event 2 Event 3 Event 4 I Task 2 I Task 2 Event 4 I Task 2 I Ta | task(s):       • Task 1: Setting up a miniMOST experiment         • Task 2: Carrying out miniMOST experiments         The project was granted to         • Washington University in St Louis         The project was sponsored by         • National Science Foundation .         The project was carried out at the following site(s):         • Department of Civil and Environmental Engineering<br>University of Illinois at Urbana-Champaign         • Washington University in St Louis         The following persons were involved in the project:         • Shirley Dyke principal investigator         • Erik A_ Johnson senior investigator         • Rup Purasinghe senior investigator         • Loy Puraschke | [-] Project: miniMOST-new         [-] Task 1         Event 1         Event 2         Event 3         Event 4         [-] Task 2         Event 1         Event 2         Image: Second Sec | Description: The miniMOST specimen is a cantilever beam. It is setup on a base plate as described in Giraldo and Myers (2004). The actuator is mounted on a L-shaped anti-spinner bracket.         Configured Equiment: <ul> <li>HSI Size 23 Non-Captive Linear Actuator</li> <li>Configured Specimen:                 <ul></ul></li></ul>  |  |
|   | Noreover, the Nami-MOSI experiment can also be unize<br>for the purposes of educational demonstration and<br>software installation debuging.<br>Objectives: 1. Demonstrate NEESgrid capabilities using<br>small-scale version of MOST 2. Initiate earthquake<br>engineers to the capabilities of the NEES collaboratory<br>Start Date: 02-01-04<br>End Date: 10-30-04<br>Keyword(s):<br>• NEESgrid<br>• Multi-site Online Simulation Test<br>• miniMOST<br>Detail of project can be accessed through<br>task(s):   |  | Ierome Lynch senior investigator     JoAnn Browning senior investigator     Acknowledgements:     This work was supported primarily by the George E.     Brown, Jr. Network for Earthquake Engineering     Simulation (NEES) Program of the National Science     Foundation as a subaward to the University of Washingto     in St Louis from the Award Number CMS-0117853.     Publication(s):         Nakata, N., Yang, G., and Spencer, B. F., 2004,         "System Requirements for Mini-MOST Experiment         MUST-Sim facilities, University of Illinois, Urbana-         Champaign         NEESgrid, 2003, "The MOST experiment, July 30         2003," University of Illinois, Urbana-Champaign.                |   | Drawing of base plate       aluminium. It is 48 inch long, 30 inch wide, and 0.375 inch thick.         Drawing of L-shape anti spinner       The L-shape anti spinner is used to prevent the actuator from spinning, when the motor rotates.         Drawing of test beam       The test beam is made of steel. It is 45 inch long, 2 inch high, and 0.25 inch thick.         List of parts       The test beam is made of steel. It is 45 inch long, 2 inch high, and 0.25 inch thick.         List of parts       This excel workbook lists (a) the parts to be manufactured and be purchased shop, and (c) the sensors to be miniMOST.         Plane view of test setup       The plane view shows the linear actuator, the LVDT, the test |  |
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## **NEES miniMOST Relationships**





## The Atkins Report



#### Vision:

- to provide an integrated system of hardware and software resources and services that
- enables scientists and engineers to explore important research and education opportunities that otherwise would not be possible.

Daniel E. Atkins, Panel Chair, Michigan http://www.cise.nsf.gov/evnt/reports/toc.htm



# Collaboratory: Earthscope





- Explore the underlying geologic structures of north America.
- Generate basic scientific understanding of the evolution of the north American continent.
- Combined with new satellite and GPS systems, EarthScope will provide a dynamic picture of forces and processes that shape the earth, including those that control earthquakes and volcanic eruptions
- EarthScope will enhance the fundamental understanding necessary for improved experimentation, simulation and prediction through NEES.



## Lessons Learned From NEES

CyberInfrastructure is fundamentally a "human problem."

Projects must engage all key communities:

- IT experts
  - $\checkmark$  Know what is possible
  - ✓ Can exploit IT advances
- Domain experts
  - ✓ Know what's appropriate
  - ✓ Can help avoid pitfalls
- Researchers and educational users
  - ✓ Understand priorities
  - ✓ Ultimately determine if infrastructure is usable





- Post-earthquake reconnaissance reports have evolved since 1994.
- Have we sufficiently preserved the information/data collected from past earthquakes? Can our students reexperience what we discovered in the field?
- The volume of information collected from earthquake reconnaissance will increase drastically in the future. How will we cope with it?
- Recommendation: Develop metadata/data models that capture time-stamped and geo-referenced events from various tools and ingest them into comprehensive data sets for immediate use by field researchers and later on for digital libraries.



## **Conclusions/ Discussion Topics (2/2)**

- Field investigators need more efficient reconnaissance tools with transparent data logging.
- Recommendations:
  - Improve/simplify tools for post-earthquake reconnaissance
  - Create a communication center/digital library with downloadable information needed by earthquake reconnaissance, e.g., maps, GPS maps, PDA, laptop tools
  - Create a reverse dataflow from a command center to the field
- Coordinate post-earthquake reconnaissance with NEES data repository, other collaboratory and digital library.
- What about a GEER collaboratory?